PROJECT: SRMS (-5 MCIU 1MSTALLED)
ASS'Y MOMENCIATURE: SERVO POWER AMPLIFIER

SYSTEM: ELECTRICAL SUBSYSTEM ASS'Y P/N: 51140F1177

	THEA	2000	NAME	T		NAO LONCH MALTILLER	ASS'Y P/N: 5174071777	SHEET:	
	REF.	FMEA REV.	NAME OTY & DRAWING REF.	FAILURE MODE	FAILURE EFFECT	HOWR / FUNC.	RATIONALE FOR ACCEPTANCE		- <u>-</u>
- 1		1	DESIGNATION	CAUSE	DN END LTEN	2/tr Criticality			i
ſ	3135	0	HOTOR DRIVE	Hone			SCREENS: A-PASS, B-PASS, C-PASS		
ŀ			RELAY GIV-6	MODE: SHORT	MOTOR WILL NOT BE DRIVEN FOR 4	DESIGN FEATURES			·
ŀ			P/N	CIRCUIT OF	OUT OF 6	**********			
			MS27743-1 AND ZENER	MOTOR PHASE	COMMUTATION	DISCRETE SENICO	Unitrata projecta apendana		
- 1		1	DICOES.	TO GROUND.	CAUSES, SPA	LEVEL OF MIL-S-	NDUCTOR DEVICES SPECIFIED TO AT LEAST THE 19500. ALL DEVICES ARE SUBJECTED TO	. IX	
ł		l i	INTER-	CAUSE(S):	FUSE AT SHOULDER WILL	RE-SCREENING BY	AN INDEPENDANT TEST HOUSE. SAMPLES OF AL	ı	1
			CONNECTION DIAGRAM	(1) DÍOĐÉ	. DE INTERAUPTED .	ANALYSIS (DPA)	TO REPLEA THE SUBJECTED TO DESTRUCTIVE DA	IYSTEAL	
	İ	1 1	2563716	FAILUME.	AND AUTO BRAKES VILL BE	PROCESSES DEVI	LE CINECE TRICORITI DE INC MANUINCIUR	ONT	1
		l i			APPLIED.	WITH SPAR-RHS-PA	A.003 AND VERIFIED BY DESIGN REVIEW.	LE	1
					ARM COMES TO		·		1 *
		i i			REST. LOSS OF ALL MODES,			1	1
- 1		1			LOSS OF LIMPING				ľ
)]	DURING END				
- 1		!			EFFECTOR CAPTURE.				1
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Z					WORST CASE				<u> </u>
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ì					UNEXPECTED		•	l	
-				· ·	MOTION. FREE JOINT.			1	
;	j	ľ	1	İ	AUTOBRAKES.		•		,
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3	1	1	i	i	REDUNDANT PATHS RENAINING				
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			1	1	1) AUTOORAKES				
1		-	!		(TO SAFE THE SYSTEM).			ĺ	
					2) JETTISON			í	
- [i			(TO SECURE DABITER).			ŀ	
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PREF	ARED BY:	HENC		SUPERCEDING DATE:	MONE			1	ñ
					- I		DATE: 11 JUL 91	C1t REV; <u>o</u>	1
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RMS/ELEC - 809

THEA REV.

NAME, Q17, & DRAWING RÉF. DESIGNATION

FMEA REF.

	S'I NUMENLLATURE: ŞI	IV INSTALLED) ERVO POWER AMPLIFIER	SYSTEM: ELECTRICAL SUBSYSTEM ASS'Y P/N: 31740F1777 SHEET:
FAILURE MODE AND CAUSE	FAILURE EFFECT ON END LIEN	HOWR / FUNC. 2/1R CRIFICALITY	RATIONALE FOR ACCEPTANCE SCREENS: A-PASS, B-PASS, C-PASS
MODE : Short	MOTOR WILL NOT BE DRIVEN FOR 4	ACCEPTANCE TES	
CIRCUIT OF MOTOR PHASE TO GROUND,	OUT OF 6 COMMUTATION CAUSES, SPA	THE SPA IS SUB AN SRU.	JECTED TO THE FOLLOWING ENVIRONMENTAL TESTING AS
CAUSE(S):	FUSE AF SHOULDER WILL	O VIBRATION:	LEVEL AND DURATION - REFERENCE TABLE 4
(1) DIODE FAILURE.	DE INTERRUPTED AND AUTO BRAKES VILL BE	O THERMAL:	PLUS 70 DEGREES C 10 -25 DEGREES C DURATION -
	APPLIED. ARM COMES TO REST. LOSS OF	THE SPA IS THEN (VIBRATION AND	TESTED AS PART OF THE JOINTS ACCEPTANCE TESTS THERMAL VACUUM TEST).
	ALL MODES. LOSS OF LIMPING DURING END EFFECTOR	ABSENCE OF THE	
	CAPTURE.	QUALIFICATION T	ESTS
		THE SPA IS SUBJ ENVIRONHENTS, I QUALIFICATION T	ECTED TO THE FOLLOWING SRU QUALIFICATION TEST HE SPA WAS ALSO TESTED AS PART OF THE JOINT ESTS.
	WORST CASE	O VIERATION:	LEVEL AND DURATION - REFERENCE TABLE 4
ĺ	UNEXPECTED MOTION, FREE	O SHOCK:	20G/11 MS/3 AXES (6 DIRECTIONS)
	JOINT. Autobrakes.	O THERMAL VAC:	+81 DEGREES C 10 -36 DEGREES C (6 CYCLES)
[O HUMIDITY:	TESTED WITH THE SHOULDER JOINT
	REDUNDANT PATHS REMAINING 1) AUTOBRAKES (10 SAFE THE	O ENC:	MIL-SID-461 AS MODIFIED BY SL-E-0002 (TEST CEO1, CEO3, CS01, CS02, CS06, REO1, REO2 (M/B), RS01)
	SYSTEM). 2) JETTISON	FEIGHT CHECKOUT	
1	(TO SECURE ORBITER).	PORS OPS CHECKLY	ST (ALL VEHICLES) JSC 16987

MOTOR DRIVE RELAY QTY-6 P/H	MODE: SHORT	HOTOR WILL HOT	ACCEPTANCE TESTS ACCEPTANCE TESTS
		BE DRIVEN FOR 4	1513
MS27743-1 AND ZENER	EIRCUIF OF MOTOR PHASE TO GROUND,	COMPUTATION	THE SPA IS SUBJECTED TO THE FOLLOWING ENVIRONMENTAL TESTING AS
INTER-	CAUSE(S):	FUSE AF	O VIBRATION: LEVEL AND DURATION - REFERENCE TABLE 4
DIAGRAM 2563716	fAILURE.	AND AUTO BRAKES	O THERMAL: PLUS 70 DEGREES C 10 -25 DEGREES C DURATION -
		APPLIED.	THE SPA IS THEN TESTED AS PART OF THE JOINTS ACCEPTANCE TESTS (VIBRATION AND THERMAL VACUUM TEST).
		ALL MODES. LOSS OF LIMPING DURING END	THE SPA'S/JOINTS UNDERGO RMS SYSIEM TESTS (TPS18 RMS STRONGBACK AND TPS52 FLAT FLOOR TESTS) WHICH VERIFIES THE ABSENCE OF THE FAILURE MODE.
		CAPTURE.	QUALIFICATION TESTS
			THE SPA IS SUBJECTED TO THE FOLLOWING SRU QUALIFICATION TEST ENVIRONMENTS. THE SPA WAS ALSO TESTED AS PART OF THE JOINT QUALIFICATION TESTS.
		WORST CASE	O VIBRATION: LEVEL AND DURATION - REFERENCE PABLE 4
1		UNEXPECTED MOTION, FREE	O SHOCK: 20G/11 MS/3 ANES (6 DIRECTIONS)
		JOINT. AUTOBRAKES.	O THERMAL VAC: +81 DEGREES C 10 -36 DEGREES C (6 CYCLES)
1		•	O HUMIDITY: TESTED WITH THE SHOULDER JOINT
		REMAINING	O ENC: MIL-SID-461 AS MODIFIED BY SL-E-0002 (TEST CEO1, CEO3, CS01, CS02, CS06, REO1, REO2 (N/B), RS01)
1 1		(TO SAFE THE SYSTEM).	FEIGHT CHECKOUT
		(TO SECURE	PDAS OPS CHECKLIST (ALL VEHICLES) JSC 16987
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If WG	SUPERCEDING DAIE:	HOHE	
	DIODES. INTER- CONNECTION DIAGRAM 2563716	DIODES. INTER- CONNECTION DIAGRAM 2563716 CAUSE(S): (1) DIODE FAILURE.	DIODES. INTER- CONNECTION DIAGRAM 2563776 CAUSE(S): (1) DIODE FAILURE. CAUSE(S): (1) DIODE FAILURE. CAUSES, SPA FUSE AF SHOULDER WILL BE INTERRUPTED AND AUTO BRAKES WILL BE APPLIED. ARM COMES TO REST. LOSS OF ALL MODES. LOSS OF LIMPING DURING END EFFECTOR CAPTURE. WORST CASE UNEXPECTED MOTION. FREE JOINT. AUTOBRAKES. REDUNDANT PATHS REMAINING 1) AUTOBRAKES (10 SAFE THE SYSTEM). 2) JETTISON (10 SECURE ORBITER).

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DATE: 11 JUL 91

CIL REV: _0

PROJECT: SRMS (-5 MCIU INSTALLED)
ASS'Y NOMENCLATURE: SERVO POWER AMPLIFIER

FMEA FME REF. REV		FATLURE MODE AND CAUSE	ASS'Y NOMENCLATURE: S FAILURE EFFECT ON END ITEM	HOWR / FUNC. RATIONALE FOR ACCEPTANCE
3135 O	MOTOR DRIVE RELAY GIT-6 P/N MS27743-1 AND ZENER DIODES, INTER- CONNECTION DIAGRAM 2563716	MODE: SHORT CIRCUIT OF MOTOR PHASE TO GROUND. CAUSE(S): (1) DIODE FAILURE.	MOTOR WILL NOT BE DRIVEN FOR 4 OUT OF 6 COMMUTATION CAUSES. SPA FUSE AT SHOULDER WILL BE THIERRUPIED AND AUTO BRAKES WILL BE APPLIED. ARM COMES TO REST. LOSS OF ALL MODES. LOSS OF LIMPING DURING END EFFECTOR CAPTURE. WORST CASE UMEMPECTED MOTION. FREE JOINT. AUTOBRAKES. REDUNDANT PATHS REMAINING 1) AUTOBRAKES (TO SAFE THE SYSTEM). 2) JETTISON (TO SECURE ORBITER).	CRITICALITY SCREEMS: A-PASS, B-PASS, C-PASS QA/IMSPECTIONS MOTOR DRIVE RELAYS ARE PROCURED AS A EEE QUALIFIED PRODUCT IN ACCORDANCE WITH THE REGUIREMENTS OF SPECIFICATION WILL-R-39016 AS REQUIRED BY SPAR-RNS-PA. 003 ADDITIONALLY ALL RELAYS ARE TOWNS SCREEMED TO THE REQUIREMENTS OF JSC SPECIFICATION ST-R. 001 AS REGUIRED BY SPAR-RNS-PA. 003. SCREEMING TESTING CONSIST OF HERMAL SHOCK, HIGH AND LOW TEMPERATURE OPERATION. INSULATION RESISTANCE, ONTACT RESISTANCE, OPERATING VOLIAGES, RADIOGRAPHIC INSPECTION AND PIND TEST. EEE PARIS INSPECTION IS PERFORMED AS REQUIRED BY SPAR-RNS-PA. 003. EACH EEE PART IS QUALIFIED AT THE PART LEVEL TO THE REQUIREMENTS OF THE APPLICABLE SPECIFICATION. ALL EEE PARTS ARE 100X SCREEMED AND BURNED IN. AS A MINIMAM. AS REQUIRED BY SPAR-RNS-PA. 003. BY THE SUPPLIER. ADDITIONALLY, EEE PARTS ARE 100X RE-SCREEMED IN ACCORDANCE WITH REQUIREMENTS. BY AN INDEPENDENT SPAR APPROVED TESTING PACIFICITY. DATA THE SUPPLIER SPARS ARE 100X RE-SCREEMED IN ACCORDANCE WITH REQUIREMENTS. BY AN INDEPENDENT SPAR APPROVED TESTING PACIFITY. DATA THE PROCURED AS REQUIRED BY PA. 003 ON A RANDOMLY SELECIED SX OF PARTS, MAXIMUM 5 PIECES WINIMAM 3 PIECES FOR WITH THE PROCURE PARTS RECEIVED. WIRE IS PACCURED TO SPECIFICATION MIL-M-22759 OR MIL-M-81381 AND INSPECTED AND TESTED TO MASA JSCHBOOD STANDAND NUMBER 95A. RECEIVING INSPECTION VERIFIES THAT ALL PARTS RECEIVED ARE AS 1DENTIFIED IN THE PROCURMENT TO THE PART APPROVED THE PARTS. PART OF THE P

P)	OJECT: SAMS (5 MC SS'Y HOMENCEATURE: \$1	IU INSTALLED) RVO POUER AMPLITIER	SYSTEM: ELECTRICAL SUBSYSTEM ASS'Y P/N: \$1740F1777
E	FAILURE EFFECT	HDUR / FUNC.	RATIONALE FOR ACCEPTANCE
	FWN LTCM	CBITICALITY	*****

THEA REF.	THEA REV.	NAME OTT & DRAWING BET, DESIGNATION	FAILURE MODE AND CAUSE	FAILURE EFFECT ON END ITEM	HDWR / FUNC. RATIONALE FOR ACCEPTANCE - 2/1R - CRITECALITY SCREENS: A-PASS, B-PASS, C-PASS
3135	0	MOTOR DRIVE RELAY QTY-6 P/N MS27743-1 AMO ZENER DIODES. INTER- CONNECTION DIAGRAM 2563716	MODE: SHORT CIRCUST OF MOTOR PHASE TO GACUND. CAUSE(S): (1) DIODE FAILURE.	MOTOR WILL NOT BE DRIVEN FOR 4 DUT OF 6 COMMITATION CAUSES. SPA FUSE AT SHOULDER WILL BE INTERRUPTED AND AUTO BRAKES WILL BE APPLIED. ARM COMES TO REST. LOSS OF ALL MODES. LOSS OF LIMPING DURING END EFFECTOR CAPTURE.	VERIFICATION TO AS DESIGN ETC., (MANDATORY INSPECTION POINT). A TEST READINESS REVIEW (TRR) WHICH INCLUDES VERIFICATION OF TEST PERSONNEL, TEST DOCUMENTS, TEST EQUIPMENT CALIBRATION/VALIDATION STATUS, AND HARDWARE CONFIGURATION IS CONVENED BY QUALITY ASSURANCE IN CONJUNCTION WITH ENGINEERING, RELIABILITY, CONFIGURATION CONTROL, SUPPLIER AS APPLICABLE, AND THE GOVENMENT REPRESENTATIVE, PRIOR TO THE START OF ANY FORMAL TESTING (ACCEPTANCE OR QUALIFICATION). ACCEPTANCE TESTING (ATP) INCLUDES AMBIENT PERFORMANCE, THERMAL AND VIBRATION TESTING, (SPAR/GOVERNMENT REP MANDATORY INSPECTION POINT). INTEGRATION OF UNIT TO JOINT SRU - INSPECTIONS INCLUDE GROWNEDING CHECKS, CONNECTORS FOR BENJ OR PUSHBACK CONTACTS, VISUAL, CLEANLINESS, INTERCONNECT WIRING AND POWER UP TEST TO THE APPROPRIATE JOINT INSPECTION TEST PROCEDURE (11P) ETC.
				WORST CASE UNEMPECTED MOTION. FREE JOINT. AUTOBRAKES. REDUNDANT PATHS REMAINING 1) AUTOBRAKES (TO SAFE THE SYSTEM). 2) JETTISON (TO SECUME ORBITER).	JOINT LEVEL PRE-ACCEPTANCE TEST INSPECTION, INCLUDES AN AUDIT OF LOWER TIER INSPECTION COMPLETION, AS BUILT CONFIGURATION VERIFICATION TO AS DESIGN ETC. JOINT LEVEL ACCEPTANCE TESTING (ATP) INCLUDES AMBINET, VIBRATION AND THERMAL-VAC TESTING. (SPAR/GOVERNMENT REP MANDATORY INSPECTION POINT). SRMS SYSTEMS INTEGRATION, THE INTEGRATION OF MECHANICAL ARM SUBASSEMBLIES AND THE FILENT CABIN EQUIPMENT TO FORM THE SRMS. INSPECTIONS ARE PERFORMED AT EACH PHASE OF INTEGRATION UNITING CHECKS, WIRING ROUTING, INTERFACE CONNECTORS FOR BENT OR PUSH BACK CONTACTS ETC. SRMS SYSTEMS TESTING - STRONGBACK AND FLAT FLOOR AMBIENT PERFORMANCE TEST. (SPAR/GOVERNMENT REP MANDATORY INSPECTION POINT)

SO40237A ATTACHMENT -PAGE 141 OF 471

DATE: 11 JUL 91

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THEA REF.	FMEA REV.	NAME, DIY & DRAWING REF. DESIGNATION	FAILURE MODE AND CAUSE	PROJECT: SRMS (-5 MC ASS'Y NOMENCLATURE: SI FAILURE EFFECT ON END ITEM	HDWR / FUNC. 2/1R CRITICALITY	RATIONALE FOR ACCEPTANCE
3135	0	MOTOR DRIVE RELAY GTY-6 P/N MS27743-1 AND ZENER DIODES. INTER- CONNECTION DIAGRAM 2563716	MODE: SHORT CIRCUIT OF MOTOR PHASE TO GROUND. CAUSE(S): (1) DIODE FAILURE.	MOTOR WILL MOT BE DRIVEN FOR 4 OUT OF 6 COMMUTATION CAUSES, SPA FUSE AT SHOULDER WILL BE INTERRIPTED AMD AUTO BRAKES WILL BE APPLIED, ARM COMES TO REST, LOSS OF ALL MODES, LOSS OF LIMPING DURING END EFFECTOR CAPTURE.	FAILURE HIST	SCREENS: A-PASS, B-PASS, C-PASS TORY DEEN NO FAILURES ASSOCIATED WITH THIS FAILURE SRMS PROGRAM.
				WORST CASE UNEXPECTED HOTION, FREE JOINT, AUTOBRAKES,		
				REDUNDANT PATHS REMAINING 1) AUTOBRAKES (TO SAFE THE SYSTEM), 2) JETTISON (TO SECURE ORBITER),		
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OJECT: SRMS (-5 MC S'Y NOMENCLATURE: SE	U INSTALLED) RVO POWER AMPLIFIER	SYSTEM: ELECTRICAL SUBSYSTEM ASS'Y P/R: 5174071177
SALLING COCCO	100110 4 40111	

	PMPA	1				N33-1 P/N: STIAUFFI// SHEET:
	FMEA REF.	FMEA REV.	NAME OTY & DRAWING REF.	FAILURE MODE AND	FAILURE EFFECT	HOWR / FUNC. RATIONALE FOR ACCEPTANCE
	3135	0	DESIGNATION	CAUSE	END ITEM	CRITICALITY SCREENS: A-PASS, B-PASS, C-PASS
			MOTOR DRIVE RELAY GTY-6 P/M MS27743-1 AND ZENER DIODES. INTER- CONNECTION DIAGRAM 2563716	MODE: SHORT CIRCUIT OF MOTOR PHASE TO GROUND. CAUSE(S): (1) DIODE FAILURE.	MOTOR WILL NOT BE DRIVEN FOR 4 OUT OF 6 COMMUTATION CAUSES. SPA FUSE AF SHOULDER WILL BE INTERRUPTED AND AUTO BRAKES WILL BE APPLIED. ARM COMES TO REST. LOSS OF ALL MODES, LOSS OF LIMPING DURING END EFFECTOR CAPTURE.	COMPUTER SUPPORTED MODES CANNOT BE USED TO COMPLETE THE MISSION. DIRECT DRIVE AND BACK-UP MODES REMAIN. IF PAYLOAD ATTACHED, THE ARM SHOULD BE MANEUVERED TO A SAFE POSITION FOR PAYLOAD RELEASE. LOSS OF NEXT REDUNDANT PATH RESULTS IN BEING ONE FAILURE AWAY FROM INABILITY TO CRADLE ARM. IF WITH SUBSEQUENT FAILURES ALL DRIVE MODES ARE LOST, THE ARM MAY BE JETTISONED. CREW HAS ABILITY TO OVERRIDE A SINGLE FAILURE. CREW ACTION APPLY BRAKES. USE DIRECT DRIVE TO POSITION OTHER JOINTS FOR JETTISON.
					WORST CASE UMEXPECTED MOTION. FREE JOINT. AUTOBRAKES.	CREW TRAINING THE CREW WILL BE TRAINED TO OBSERVE WHETHER THE ARM IS RESPONDING PROPERLY TO COMMANDS. IF IT ISN'T APPLY BRAKES. MISSION CONSTRAINT
	ŀ				REDUNDANT PAIHS REMAINING 1) AUTOBRAKES (10 SAFE THE SYSTEM). 2) JETTISON (10 SECURE ORBITER).	OPERATE UNDER VERNIER RATES WITHIN 10 FT OF STRUCTURE. THE OPERATOR MUST BE ABLE TO DETECT THAT THE ARM IS RESPONDING PROPERLY TO COMMANDS VIA WINDOW AND/OR CCTV VIEWS DURING ALL ARM OPERATIONS. AUTO TRAJECTORIES MUST BE DESIGNED TO COME NO CLOSER THAN 5 FT FROM STRUCTURE.
						VERIFY SPA 28V FAIL FLAG IN THE ABE DATA IN COMPUTER CONTROLLED MODE VERIFY EACH JOINT DRIVES OMES ONLINE INSTALLATION NONE OMES ONLINE TURNAROUND VERIFY SPA 28V FAIL FLAG IN ABE DATA. FOR EACH JOINT IN SINGLE MODE VERIFY TACHO SIGNATURE.
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PREPARED BY:

CRITICAL ITEMS LIST

SUPERCEDING DATE: NONE

DATE: 11 JUL 91

CIL REV: 0